## Programmable controllers (up to 43 I/O)





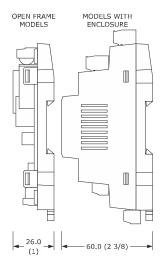


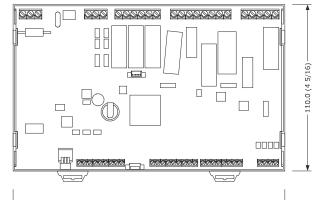
- blind open frame models or with enclosure
- power supply 115... 230 VAC
- 10 analogue inputs, 16 in the plus controllers (can be configured also for dry contact
- 3 dry contact digital inputs
- 2 high voltage digital inputs
- 4 analogue outputs, 8 in the plus controllers
- 9 electro-mechanical relay digital outputs, 14 in the plus controllers
- INTRABUS port (RS-485 MODBUS master/slave by connecting the serial interface EVIF22ISX)
- RS-485 MODBUS slave port
- RS-485 port (MODBUS master/slave, BACnet MS/TP) (1)
- CAN port
- models with Ethernet port (MODBUS TCP, WebServer, BACnet IP)  $^{\left(1\right)}$
- the BACnet communication protocol can be used only in alternative to the Web Server

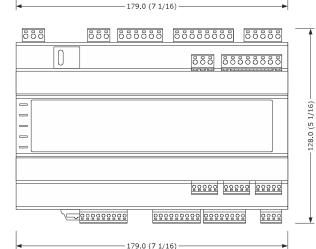
| Kind of controller | Purchasing codes | Version          | Power supply | 1/0 | Communication ports |
|--------------------|------------------|------------------|--------------|-----|---------------------|
| standard           | EPG90            | blind open frame |              | 28  |                     |
| standard           | EPG9B            | blind with       |              | 28  |                     |
|                    |                  | enclosure        |              |     | TTL, INTRABUS,      |
| plus               | EPG9BXQ          | cieca con        |              | 43  | 2 RS-485, CAN       |
|                    |                  | contenitore      |              |     | and USB             |
| plus               | EPG9BHQ          | cieca con        |              | 43  |                     |
|                    |                  | contenitore      | 115 230      |     |                     |
| standard           | EPG9OHX          | blind open frame | VAC          | 28  |                     |
| standard           | EPG9BHX          | blind with       |              | 28  |                     |
|                    |                  | enclosure        |              |     | TTL, INTRABUS,      |
| plus               | EPG9BXP          | blind with       | ]            | 43  | 2 RS-485, CAN,      |
|                    |                  | enclosure        |              |     | USB and Ethernet    |
|                    | EPG9BHP          | blind with       | 1            | 43  | ]                   |
| plus               |                  | enclosure        |              |     |                     |

### MEASUREMENTS AND INSTALLATION

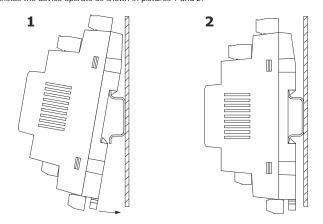
Measurements in mm (inches). To be fitted on a DIN rail, in a control panel.



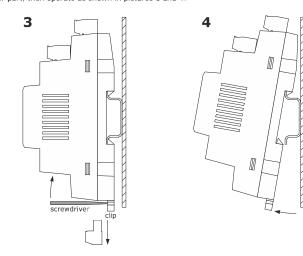




To install the device operate as shown in pictures 1 and 2



To remove the device, first remove any screw-in removable terminal blocks mounted in the lower part, then operate as shown in pictures 3 and 4.



To install the device again press down the clip before.

#### INSTALLATION PRECAUTIONS

- Ensure that the working conditions are within the limits stated in the TECHNICAL SPECIFICATIONS section
- Do not install the device close to heat sources, equipment with a strong magnetic field, in places subject to direct sunlight, rain, damp, excessive dust, mechanical vibrations
- In compliance with safety regulations, the device must be installed properly to ensure adequate protection from contact with electrical parts. All protective parts must be fixed in such a way as to need the aid of a tool to remove them

#### 2 ELECTRICAL CONNECTION



To reduce any electromagnetic interference connect the power cables as far away as possible from the signal cables and, if necessary, connect to a RS-485 MODBUS network and/or a CAN network by using a twisted pair.

## 2.1.1 Connectors available both in standard and plus controllers

Description of connectors.

| N. | DESCRIPTION  |  |  |
|----|--------------|--|--|
| V~ | device nower |  |  |

- e power supply (115... 230 VAC) V~ device power supply (115... 230 VAC)
- N. DESCRIPTION

## DIHV1 high voltage digital input; DI1

- DIHV2 high voltage digital input; DI2
- COM high voltage digital inputs common contact

# N. DESCRIPTION

- NO1 K1 digital output normally open contact (3 A res. @ 250 VAC)
- CO1 K1 digital output common contact
- NO2 K2 digital output normally open contact (3 A res. @ 250 VAC) CO2 K2 digital output common contact
- NO3 K3 digital output normally open contact (3 A res. @ 250 VAC)
- CO3 K3 digital output common contact

## N. DESCRIPTION

- NO4 K4 digital output normally open contact (3 A res. @ 250 VAC)
- CO4 K4 digital output common contact NO5 K5 digital output normally open contact (2 A res. @ 250 VAC)
- CO5 K5 digital output common contact
- NO6 K6 digital output normally open contact (3 A res. @ 250 VAC)
- CO6 K6 digital output common contact NO7 K7 digital output normally open contact (8 A res. @ 250 VAC)
- CO7 K7 digital output common contact

## N. DESCRIPTION

- CO8 K8 digital output common contact
- NC9 K9 digital output normally closed contact
- NO9 K9 digital output normally open contact (3 A res. @ 250 VAC)
- CO9 K9 digital output common contact

## N. DESCRIPTION

- CAN+ signal + CAN port CAN- signal - CAN port
- A1/+ signal + RS-485 MODBUS slave port
- B1/- signal RS-485 MODBUS slave port
- A2/+ signal + RS-485 port (MODBUS master/slave, BACnet MS/TP)
- B2/- signal RS-485 port (MODBUS master/slave, BACnet MS/TP) IB data INTRABUS port
- GND reference (GND)
- 12V power supply remote user interfaces (13 VDC)

can be configured also for dry contact digital input

The actual UNI-PRO 3.13 version implements a BACnet® standardized device profile B-ASC which doesn't require the managing of Scheduler and Calendar objects, instead required for the

| N.  | DESCRIPTION   |
|-----|---|
| GND | reference (GND)   |
| DI3 | digital input 3 (dry contact and for pulse trains up to 2 KHz); DI3 |
| DI4 | digital input 4 (dry contact and for pulse trains up to 2 KHz); DI4 |
| DI5 | digital input 5 (dry contact and for pulse trains up to 2 KHz); DI5 |
| AI1 | analogue input 1 (for PTC, NTC or Pt 1000 probes); Al1              |
|     | can be configured also for dry contact digital input                |
| AI2 | analogue input 2 (for PTC, NTC or Pt 1000 probes); AI2              |

- analogue input 3 (for PTC, NTC or Pt 1000 probes); AI3 can be configured also for dry contact digital input analogue input 4 (for PTC, NTC or Pt 1000 probes); AI4 can be configured also for dry contact digital input
- analogue input 5 (for PTC, NTC or Pt 1000 probes); AI5 can be configured also for dry contact digital input

### N. DESCRIPTION

- GND reference (GND) analogue input 6 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI6
- can be configured also for dry contact digital input analogue input 7 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI7
- can be configured also for dry contact digital input analogue input 8 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI8
- can be configured also for dry contact digital input analogue input 9 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20
- mA transducers): AI9 can be configured also for dry contact digital input Al10 analogue input 10 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20
- mA transducers); AI10
- can be configured also for dry contact digital input
- +5V power supply 0-5 V ratiometric transducers (5 VDC)

## VS power supply transducers (13 VDC)

- N. DESCRIPTION
- AO1 analogue output 1 (for 0-10 V or PWM) AO2 analogue output 2 (for 0-10 V or PWM) AO3 analogue output 3 (for 0-10 V or PWM)
- AO4 analogue output 4 (for 0-10 V or PWM) 2.1.2 Connectors only available in the plus controllers

Description of connectors.

- N. DESCRIPTION NO10 K10 digital output normally open contact (8 A res. @ 250 VAC) CO10 K10 digital output common contact NC10 K10 digital output normally closed contact NO11 K11 digital output normally open contact (5 A res. @ 250 VAC) CO11 K11 digital output common contact NO12 K12 digital output normally open contact (5 A res. @ 250 VAC) CO12 K12 digital output common contact NO13 K13 digital output normally open contact (5 A res. @ 250 VAC)
- CO13 K13 digital output common contact
- NO14 K14 digital output normally open contact (5 A res. @ 250 VAC) CO14 K14 digital output common contact
- N. DESCRIPTION GND reference (GND) Al11 analogue input 11 (for PTC, NTC or Pt 1000 probes); Al11 can be configured also for dry contact digital input Al12 analogue input 12 (for PTC, NTC or Pt 1000 probes); Al12
- can be configured also for dry contact digital input analogue input 13 (for PTC, NTC or Pt 1000 probes); Al 13 can be configured also for dry contact digital input
- analogue input 14 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI14 can be configured also for dry contact digital input

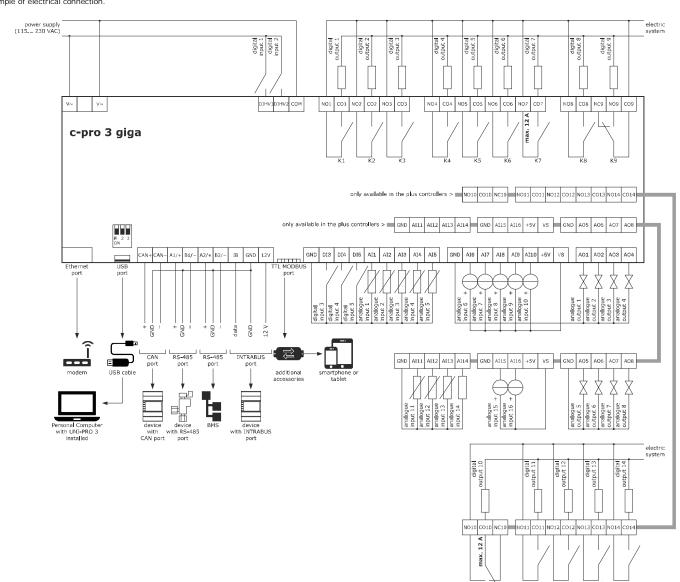
## N. DESCRIPTION

- GND reference (GND)
- analogue input 15 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI15
- can be configured also for dry contact digital input Al16 analogue input 16 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI16
- can be configured also for dry contact digital input +5V power supply 0-5 V ratiometric transducers (5 VDC)
- VS power supply transducers (13 VDC)

## N. DESCRIPTION (fo models EPG9BXP and EPG9BHP)

- GND reference (GND) AO5 analogue output 5 (for 0-10 V or PWM)
- AO6 analogue output 6 (for 0-10 V or PWM)
- AO7 analogue output 7 (for 0-10 V or PWM) AO8 | analogue output 8 (for 0-10 V or PWM)
- N. DESCRIPTION (for models EPG9BXQ and EPG9BHQ)
- GND reference (GND)
- DI6 digital input 6 (dry contact); DI6 DI7 digital input 7 (dry contact); DI7
- DI8 digital input 8 (dry contact); DI8
- DI9 digital input 9 (dry contact); DI9

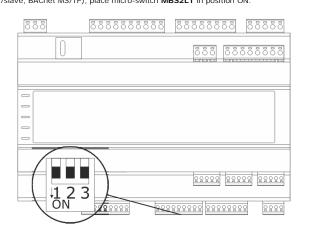
#### Electrical connection 2.2 Example of electrical connection.



#### Fitting the termination resistor of RS-485 networks and CAN network

To fit the CAN network termination resistor, place micro-switch CANLT in position ON To fit the termination resistor of the RS-485 network connected to the RS-485 MODBUS slave

port, place micro-switch  $\ensuremath{\mathsf{MBS1LT}}$  in position ON. To fit the termination resistor of the RS-485 network connected to the RS-485 port (MODBUS master/slave, BACnet MS/TP), place micro-switch MBS2LT in position ON.



### PRECAUTIONS FOR ELECTRICAL CONNECTION

- If using an electrical or pneumatic screwdriver, adjust the tightening torque  $% \left( 1\right) =\left( 1\right) \left( 1\right) \left($
- If the device has been moved from a cold to a warm place, the humidity may have caused condensation to form inside. Wait about an hour before switching on the power Make sure that the supply voltage, electrical frequency and power are within the set limits. See the section  $\it TECHNICAL\ SPECIFICATIONS$
- Disconnect the power supply before doing any type of maintenance Do not use the device as safety device
- For repairs and for further information, contact the EVCO sales network.

| ·  |                  |  |  | 0, 1 20 11111              | mpat resistar    |  |
|--|------------------|--|--|----------------------------|------------------|--|
|  |                  |  |  | transducers:               | Resolution:      |  |
| 3 TECHNICAL SPECIFIC                                 | ATIONS           |  |  | Power supply               | remote user int  |  |
|  |                  | i  |  | Power supply               | transducers:     |  |
| Purpose of the control device:                       |                  | Function contro                              |  |                            |                  |  |
| Construction of the control device:                  |                  | Built-in electro                             |  | Power supply 0-5 V ratiome |                  |  |
| Container:   |                  | Grey, self-extir                             | nguishing.                             | shing.                     |                  |  |
| Category of heat and fire resist                     | ance:            | D.   |  | Digital inputs:            |                  |  |
| Measurements:  |                  | ı  |  |                            |                  |  |
| 10 DIN modules: 179.0 x 110                          |                  |  | es: 179.0 x 128.0 x 60.0 mm            | Dry comact.                |                  |  |
| (7 1/16 x 4 5/16 x 1 in) th                          | ne open frame    | ,  | 16 x 2 3/8 in) the models with         | 1                          |                  |  |
| models   |                  | enclosure.                                   |  | High voltage contac:       |                  |  |
| Mounting methods for the cont                        |                  |  | a DIN rail, in a control panel.        | - Analogue outputs:        |                  |  |
| Degree of protection provided I                      | by the covering: | ı  |  |                            |                  |  |
| IP00 the open frame models                           |                  | IP40 the front                               | of the models with enclosure.          | 0-10 V sig-                | Minimum ap       |  |
| Connection method:                                   |                  |  |  | nal:                       | ance:            |  |
| screw terminal blocks for wi                         | •                |  | ew terminal blocks for wires up        |                            | Resolution:      |  |
| mm <sup>2</sup> and 2.5 mm <sup>2</sup> the open fra | ame models       |  | nd 2.5 mm <sup>2</sup> the models with | PWM signal:                | Power supply:    |  |
|  |                  | enclosure                                    |  |                            | Frequency:       |  |
| removable clamp terminal blocks for wires up         |                  | Pico-Blade connector                         |  |                            | Duty:            |  |
| to 1.5 mm <sup>2</sup> the plus controllers          |                  |  |  |                            | Resolution:      |  |
| Micro-USB connector                                  |                  | RJ45 F telephone connector (according to the |  | Digital outputs            | s:               |  |
|  |                  | model).                                      |  |                            |                  |  |
| Maximum permitted length for                         | connection cabi  | ı  |  |                            |                  |  |
| Power supply: 10 m (32.8 ft)                         |                  | Analogue inputs: 10 m (32.8 ft)              |  |                            |                  |  |
| Auxiliary power supply and 0-                        |                  | Digital inputs:                              | 10 m (32.8 ft)                         |                            |                  |  |
| transducer power supply: 10 m                        |                  |  |  |                            |                  |  |
| 0-10 V analogue outputs: 10 m                        |                  | PWM analogue outputs: 1 m (3.28 ft)          |  |                            |                  |  |
| Digital outputs: 100 m (328 ft)                      |                  |  | t: 10 m (32.8 ft)                      |                            |                  |  |
| RS-485 MODBUS port: 1,000 n                          |                  | USB port: 1 m                                | · · · · · · · · · · · · · · · · · · ·  | The device gua             | arantees:        |  |
|  |                  | 30 ft), baud rate: 20,000 baud               |  | - reinforced in            | nsulation betwe  |  |
|  |                  | ft), baud rate: 50,000 baud                  |  | - reinforced in            | nsulation betwe  |  |
|  |                  | ), baud rate: 125,000 baud                   |  | - basic insula             | tion between re  |  |
|  | 50 m (164 ft),   | baud rate: 500,                              |  |                            | nsulation betwe  |  |
| Operating temperature:                               |                  | From -10 to 55 °C (from 14 to 131 °F).       |  |                            | nsulation betwe  |  |
| Storage temperature:                                 |                  | From -20 to 70 °C (from -4 to 158 °F).       |  | ' '                        | V1 and DIHV2)    |  |
| Operating humidity:                                  |                  | Relative humidity without condensate from 5  |  | _                          | tion between liv |  |
|  |                  | to 95%.                                      |  | Type 1 or Type             |                  |  |
| Pollution status of the control of                   | levice:          | 2.   |  |                            | tures of Type    |  |
| Compliance:  |                  |  |  | tions:                     |                  |  |
| RoHS 2011/65/EC                                      | WEEE 2012/19     | /19/EU REACH (EC) Regulation 1907/2006       |  | 1 TTL MODBUS               | -                |  |
| FMC 2014/30/FU                                       | 1                | LVD 2014/35/L                                |  |                            | - p              |  |
| EMC 2014/30/EU                                       | •                | LVD 2014/35/L                                |  |                            | •                |  |

|  |  | K10 L                                     | K11 K12   | K13 K14  |  |  |
|--|--|---|---|--|--|--|
| Power supply:                          |  |   | 115 230 VAC (+10% -15%), 50/60 Hz   |  |  |  |
| 10                                     |  |   | (±3 Hz), max. 16 VA, 20 VA in the plus con-                                   |  |  |  |
|  |  |   | trollers.   |  |  |  |
| Earthing metho                         | ods for the contr  | ol device:                                | None.   |  |  |  |
|  | -withstand voltag  | ge:                                       | 2.5 KV.   |  |  |  |
| Over-voltage c                         |  |   | 11.   |  |  |  |
| Software class                         | and structure:   |   | Α.  |  |  |  |
| Clock:                                 |  |   |   | y lithium battery.   |  |  |
| Clock drift:                           | autonomy in the  | a sheepee of a                            | ≤ 30s/month at 25°C (77 °F). > 6 months at 25 °C (77 °F).                     |  |  |  |
| power supply:                          | autonomy in an   | absence of a                              | > 0 1110111113 41   | 25 C (77 F).   |  |  |
| Clock battery c                        | charging time:   |   | 24h (the batt   | 24h (the battery is charged by the power                                     |  |  |
|  |  |   | supply of the d   |  |  |  |
| Analogue input                         | ts:  |   | 5 for PTC, NTC  | 5 for PTC, NTC or Pt 1000 probes, 8 in the                                   |  |  |
|  |  |   | plus controllers (can be configured also for                                  |  |  |  |
|  |  |   | dry contact digital input)  |  |  |  |
|  |  |   | 1   | C or Pt 1000 probes, 0-5 V, 0-<br>A or 4-20 mA transducers, 8 in             |  |  |
|  |  |   |   |  |  |  |
|  |  |   |   | the plus controllers (can be configured also for dry contact digital input). |  |  |
| PTC probes:                            | Sensor type:   |   |   | 90 Ω @ 25 °C, 77 °F)   |  |  |
|  | Measurement f  | ield:                                     | 1   | 0 °C (from -58 to 302 °F)  |  |  |
|  | Resolution:  |   | 0.1 °C (1 °F).  |  |  |  |
| NTC probes:                            | Sensor type:   |   | †   | @ 25 °C, 77 °F)  |  |  |
|  | Measurement f  | ield:                                     | 1   | 0 °C (from -58 to 248 °F)  |  |  |
| 1200                                   | Resolution:  |   | 0.1 °C (1 °F).  |  |  |  |
| Pt 1000                                |  |   | 1 KΩ @ 0 °C, 32 °F  |  |  |  |
| probes:                                | Measurement f<br>Resolution:   | ield:                                     | from -100 to 400 °C (from -148 to 752 °F)                                     |  |  |  |
| 0-5 V trans-                           |  |   | 1 °C (1 °F).<br>≥ 10 KΩ   | ≥ 10 KΩ  |  |  |
| ducers:                                | Resolution:  | e.  | 0.01 V.   |  |  |  |
| 0-10 V trans-                          |  | ce:                                       | ≥ 10 KΩ   |  |  |  |
| ducers:                                | Resolution:  |   | 0.01 V.   |  |  |  |
| 0/4-20 mA                              |  | :e:                                       | ≤ 200 Ω   |  |  |  |
| transducers:                           | Resolution:  |   | 0.01 mA.  |  |  |  |
|  | remote user inter  | rfaces:                                   |   | % -10%, 150 mA max.  |  |  |
| Power supply to                        | ransducers:  |   |   | 0 % -10%, 100 mA max.  |  |  |
| Dawer supply (                         | V ratiometric  | t-anoducors:                              | (+40 mA max. in the plus controllers).  5 VDC, ±15 %, 20 mA max. (+40 mA max. |  |  |  |
| Power supply o                         | 0-5 V ratiometric  | . transducers.                            | in the plus conf  |  |  |  |
| Digital inputs:                        |  |   |   | and for pulse trains up to 2 KHz   |  |  |
|  |  |   | 2 high voltage.   |  |  |  |
| Dry contact:                           |  | Contact type:                             |   | 3.3 VDC, 1 mA  |  |  |
|  |  | Power supply:                             |   |  |  |  |
| High voltage co                        |  | Power supply:                             | -   | 115 230 VAC.   |  |  |
| Analogue outpu                         | uts:   |   |   | 4 for 0-10 V or PWM signal, 8 in the plus con-                               |  |  |
| 0.10 V sig                             | I the leading one  | " -t-t- impost                            | trollers  |  |  |  |
| 0-10 V sig- Minimum appl<br>nal: ance: |  | ilcable illipeu- i                        | 1 ΚΩ  |  |  |  |
| Ha                                     | Resolution:  |   | 0.01 V.   |  |  |  |
| PWM signal:                            | Power supply:  |   | 0 10 VDC, 10 mA max.  |  |  |  |
| _                                      | Frequency:   |   | 10 Hz 2 KHz   |  |  |  |
| Duty:                                  |  |   | 0 100%.   |  |  |  |
| Resolution:                            |  | 1% up to 500 Hz, 5% up to 2 KHz.          |   |  |  |  |
| Digital outputs:                       |  | 2 with SPST electro-mechanical relay, 2 A |   |  |  |  |
|  |  | res. @ 250 VAC, 6 in the plus controllers |   |  |  |  |
|  |  |   | 5 with SPST electro-mechanical relay, 3 A                                     |  |  |  |
|  |  |   | res. @ 250 VAC  1 with SPDT electro-mechanical relay, 3 A                     |  |  |  |
|  |  |   | res. @ 250 VAC, 2 in the plus controllers                                     |  |  |  |
|  |  | 1 with SPST electro-mechanical relay, 8 A |   |  |  |  |
|  |  |   | res. @ 250 VAC.   |  |  |  |
| The device gua                         |  |   |   |  |  |  |
|  |  |   | and relay output  | S  |  |  |
|  | nsulation between  |   |   | o acoun  |  |  |
|  | <ul> <li>basic insulation between relay outputs belong</li> <li>reinforced insulation between live parts and \$</li> </ul> |   |   | e group  |  |  |
|  |  |   |   | 1 K3) and high voltage digital   |  |  |

- reinforced insulation between "group 1" of relay outputs (K1... K3) and high voltage digital

Type 1.

EVIF22ISX)

1 INTRABUS port (RS-485 MODBUS mas-

ter/slave by connecting the serial interface

basic insulation between live parts of opposite polarity (line-neutral).

Additional features of Type 1 or Type 2 ac- C.

| •          | 1 RS-485 port (MODBUS master/slave, BAC-net MS/TP) |
|------------|--|
| 1 CAN port | 1 USB port   |

according to the model, Ethernet port (MODBUS TCP, WebServer, BACnet IP).

The device must be disposed of according to local regulations governing the collection of electrical and electronic waste.

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EVCO S.p.A.