c-pro 3 giga IoT

Programmable controllers (up to 43 I/O)







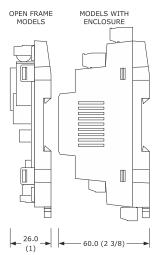
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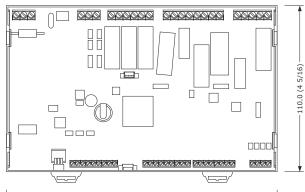
- blind open frame models or with enclosure
- power supply 115... 230 VAC
- 10 analogue inputs, 16 in the plus controllers (can be configured also for dry contact digital input)
- 3 dry contact digital inputs
- 2 high voltage digital inputs
- 4 analogue outputs, 8 in the plus controllers
- 9 electro-mechanical relay digital outputs, 14 in the plus controllers, 11 in the U-EEV and B-EEV controllers
- TTL MODBUS port
- INTRABUS port (RS-485 MODBUS master/slave by connecting the serial interface EVIF22ISX)
- RS-485 MODBUS slave port
- RS-485 port (MODBUS master/slave, BACnet MS/TP)
- CAN port
- USB port
- models with 2 integrated unipolar or bipolar stepper electronic expansion valves driver Ethernet port (MODBUS TCP, WebServer, BACnet IP)
- - the device must be programmed with version 3.24 of UNI-PRO 3 or higher

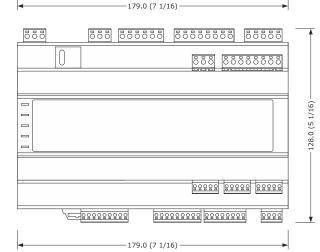
Kind of controller	Purchasing codes	Version	Power supply	I/O	Kind of integrated electronic expansion valves driver	Comm. ports
standard	EPG90IX	blind open frame		28	none	
standard	EPG9BIX	blind with		28	none	
		enclosure				TTL,
plus	EPG9BIP	blind with		43	none	INTRABUS,
		enclosure	115 230			2 RS-485,
plus	EPG9BIQ	blind with	VAC	43	none	CAN,
		enclosure				USB and
U-EEV	EPG9BIU	blind with		36	2 unipolar stepper	Ethernet
		enclosure			type	
B-EEV	EPG9BIW	blind with		36	2 bipolar stepper	
		enclosure			type	

MEASUREMENTS AND INSTALLATION

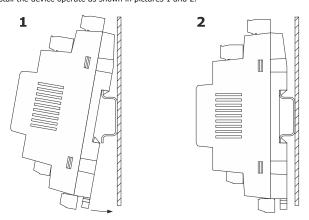
surements in mm (inches). To be fitted on a DIN rail, in a control panel



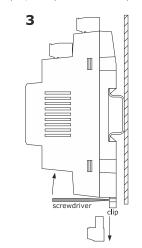


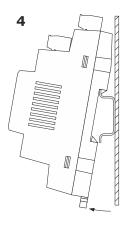


To install the device operate as shown in pictures 1 and 2



To remove the device, first remove any screw-in removable terminal blocks mounted in the lower part, then operate as shown in pictures 3 and 4.





To install the device again press down the clip before.

INSTALLATION PRECAUTIONS

Ensure that the working conditions are within the limits stated in the TECHNICAL SPECIFICATIONS section

Do not install the device close to heat sources, equipment with a strong magnetic field, in places subject to direct sunlight, rain, damp, excessive dust, mechanical vibrations

In compliance with safety regulations, the device must be installed properly to ensure adequate protection from contact with electrical parts. All protective parts must be fixed in such a way as to need the aid of a tool to remove them

2 ELECTRICAL CONNECTION



Use cables of an adequate section for the current running through them

To reduce any electromagnetic interference connect the power cables as far away as possible from the signal cables and, if necessary, connect to a RS-485 MODBUS network and/or a CAN network by using a twisted pair.

2.1.1 Connectors available both in standard and plus controllers

Description of connectors.

N.	DESCRIPTION

V~ device power supply (115... 230 VAC) V~ device power supply (115... 230 VAC)

N. DESCRIPTION

DIHV1 high voltage digital input; DI1

DIHV2 high voltage digital input; DI2

COM high voltage digital inputs common contact

N. DESCRIPTION

NO1 K1 digital output normally open contact (3 A res. @ 250 VAC)

CO1 K1 digital output common contact NO2 K2 digital output normally open contact (3 A res. @ 250 VAC)

CO2 K2 digital output common contact NO3 K3 digital output normally open contact (3 A res. @ 250 VAC)

CO3 K3 digital output common contact

N. DESCRIPTION

NO4 K4 digital output normally open contact (3 A res. @ 250 VAC) CO4 K4 digital output common contact

NO5 K5 digital output normally open contact (2 A res. @ 250 VAC)

CO5 | K5 digital output common contact NO6 K6 digital output normally open contact (3 A res. @ 250 VAC)

CO6 K6 digital output common contact

NO7 K7 digital output normally open contact (8 A res. @ 250 VAC)

CO7 K7 digital output common contact

N. DESCRIPTION

digital output normally oper CO8 K8 digital output common contact

NC9 K9 digital output normally closed contact

NO9 K9 digital output normally open contact (3 A res. @ 250 VAC) CO9 K9 digital output common contact

N. DESCRIPTION CAN+ signal + CAN port

CAN- signal - CAN port

A1/+ signal + RS-485 MODBUS slave port

B1/- signal - RS-485 MODBUS slave port A2/+ signal + RS-485 port (MODBUS master/slave, BACnet MS/TP)

B2/- signal - RS-485 port (MODBUS master/slave, BACnet MS/TP)

IB data INTRABUS port

GND reference (GND)

12V power supply remote user interfaces (13 VDC)

N. DESCRIPTION

GND reference (GND)

DI3 digital input 3 (dry contact and for pulse trains up to 2 KHz); DI3 DI4 digital input 4 (dry contact and for pulse trains up to 2 KHz); DI4

DI5 digital input 5 (dry contact and for pulse trains up to 2 KHz); DI5 AI1 | analogue input 1 (for PTC, NTC or Pt 1000 probes): AI1

can be configured also for dry contact digital input

analogue input 2 (for PTC, NTC or Pt 1000 probes); AI2 can be configured also for dry contact digital input

analogue input 3 (for PTC, NTC or Pt 1000 probes); AI3

can be configured also for dry contact digital input analogue input 4 (for PTC, NTC or Pt 1000 probes); AI4 can be configured also for dry contact digital input

analogue input 5 (for PTC, NTC or Pt 1000 probes); AI5 can be configured also for dry contact digital input

N. DESCRIPTION

GND reference (GND) analogue input 6 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI6

can be configured also for dry contact digital input analogue input 7 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI7

can be configured also for dry contact digital input analogue input 8 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI8

can be configured also for dry contact digital input analogue input 9 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI9

can be configured also for dry contact digital input analogue input 10 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20

mA transducers): AI10 can be configured also for dry contact digital input

+5V power supply 0-5 V ratiometric transducers (5 VDC)

VS power supply transducers (13 VDC)

AO4 analogue output 4 (for 0-10 V or PWM)

N. DESCRIPTION AO1 analogue output 1 (for 0-10 V or PWM) AO2 analogue output 2 (for 0-10 V or PWM) AO3 analogue output 3 (for 0-10 V or PWM)

2.1.2 Connectors only available in the plus controllers

Description of connectors.

N. DESCRIPTION NO10 K10 digital output normally open contact (8 A res. @ 250 VAC) CO10 K10 digital output common contact NC10 K10 digital output normally closed contact

NO11 K11 digital output normally open contact (2 A res. @ 250 VAC) CO11 K11 digital output common contact

NO12 K12 digital output normally open contact (2 A res. @ 250 VAC) CO12 K12 digital output common contact

NO13 K13 digital output normally open contact (2 A res. @ 250 VAC) CO13 K13 digital output common contact NO14 K14 digital output normally open contact (2 A res. @ 250 VAC)

CO14 K14 digital output common contact

N. DESCRIPTION (for model EPG9BIP)

GND reference (GND) AO5 analogue output 5 (for 0-10 V or PWM) AO6 analogue output 6 (for 0-10 V or PWM) AO7 analogue output 7 (for 0-10 V or PWM) AO8 analogue output 8 (for 0-10 V or PWM)

N. DESCRIPTION (for model EPG9BIQ)

GND reference (GND) DI6 digital input 6 (dry contact); DI6

DI7 digital input 7 (dry contact); DI7

DI8 digital input 8 (dry contact); DI8 DI9 digital input 9 (dry contact); DI9

2.1.3 Connectors only available in the U-EEV and B-EEV controllers

N. DESCRIPTION

NO10 K10 digital output normally open contact (5 A res. @ 250 VAC)

CO10 K10 digital output common contact NO11 K11 digital output normally open contact (5 A res. @ 250 VAC)

CO11 K11 digital output common contact

N. DESCRIPTION REF power supply engine unipolar or bipolar stepper electronic expansion valve 1

(12 VDC, 260 mA max. winding in the U-EEV controllers, 12 VDC, 200 mA max. winding in the B-EEV controllers)

OUT4 output 4 unipolar or bipolar stepper electronic expansion valve 1 engine control OUT3 output 4 unipolar or bipolar stepper electronic expansion valve 1 engine control OUT2 output 4 unipolar or bipolar stepper electronic expansion valve 1 engine control

OUT1 output 4 unipolar or bipolar stepper electronic expansion valve 1 engine control

N. DESCRIPTION power supply engine unipolar or bipolar stepper electronic expansion valve 2 REF

(12 VDC, 260 mA max. winding in the U-EEV controllers, 12 VDC, 200 mA max. winding in the B-EEV controllers) OUT4 | output 4 unipolar or bipolar stepper electronic expansion valve 2 engine control

2.1.4 Connectors available both in the plus controllers and in the U-EEV and B-EEV

OUT3 output 4 unipolar or bipolar stepper electronic expansion valve 2 engine control OUT2 output 4 unipolar or bipolar stepper electronic expansion valve 2 engine control

OUT1 output 4 unipolar or bipolar stepper electronic expansion valve 2 engine control

controllers Description of connectors.

N. DESCRIPTION

GND reference (GND)

analogue input 11 (for PTC, NTC or Pt 1000 probes); AI11 can be configured also for dry contact digital input

AI12 analogue input 12 (for PTC, NTC or Pt 1000 probes); AI12 can be configured also for dry contact digital input

AI13 analogue input 13 (for PTC, NTC or Pt 1000 probes); AI13

can be configured also for dry contact digital input

AI14 analogue input 14 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI14

can be configured also for dry contact digital input

N. DESCRIPTION GND reference (GND)

analogue input 15 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 AI15 mA transducers); AI15

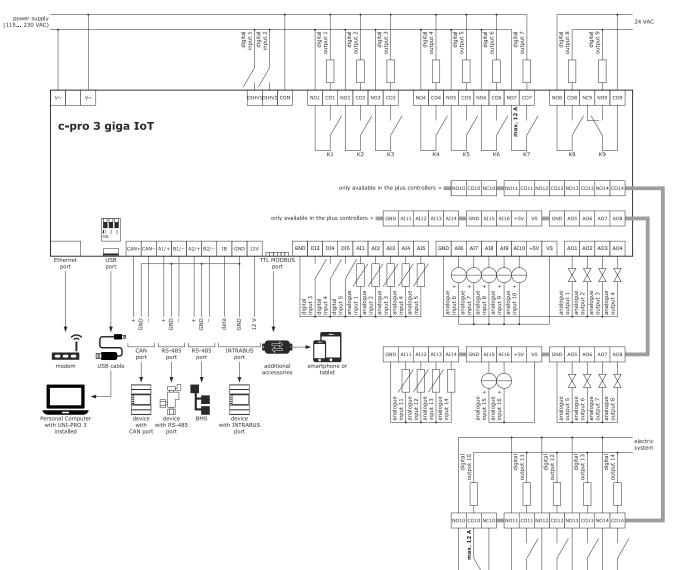
can be configured also for dry contact digital input AI16 analogue input 16 (for PTC, NTC or Pt 1000 probes, 0-5 V, 0-10 V, 0-20 mA or 4-20 mA transducers); AI16

can be configured also for dry contact digital input +5V power supply 0-5 V ratiometric transducers (5 VDC)

VS power supply transducers (13 VDC)

Electrical connection

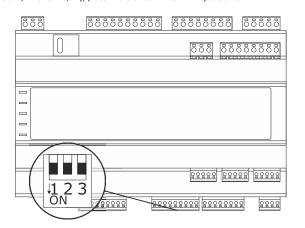
Example of electrical connection for standard and plus controllers.



Fitting the termination resistor of RS-485 networks and CAN network

To fit the CAN network termination resistor, place micro-switch ${\bf CANLT}$ in position ON. To fit the termination resistor of the RS-485 network connected to the RS-485 MODBUS slave port, place micro-switch MBS1LT in position ON.

To fit the termination resistor of the RS-485 network connected to the RS-485 port (MODBUS master/slave, BACnet MS/TP), place micro-switch MBS2LT in position ON.



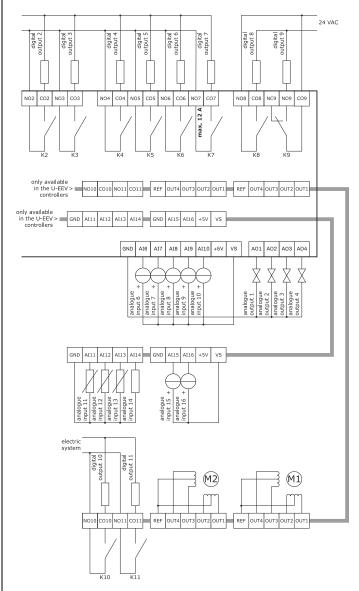
PRECAUTIONS FOR ELECTRICAL CONNECTION

- If using an electrical or pneumatic screwdriver, adjust the tightening torque If the device has been moved from a cold to a warm place, the humidity may have
- caused condensation to form inside. Wait about an hour before switching on the power Make sure that the supply voltage, electrical frequency and power are within the set limits. See the section TECHNICAL SPECIFICATIONS
- Disconnect the power supply before doing any type of maintenance $% \left(1\right) =\left(1\right) \left(1\right) \left($
- Do not use the device as safety device

- For repairs and for further information, contact the EVCO sales network.				
3 TECHNICAL SPECIFICATIONS				
5 FECHNICAL SPECIFIC	ATIONS			
Purpose of the control device:		Function controller.		
Construction of the control dev	rice:	Built-in electronic device.		
Container:		Grey, self-extinguishing.		
Category of heat and fire resis	tance:	D.		
Measurements:				
10 DIN modules: 179.0 x 110	0.0 x 26.0 mm	10 DIN modules: 179.0 x 128.0 x 60.0 mm		
(7 1/16 x 4 5/16 x 1 in) the	ne open frame	(7 1/16 x 5 1/16 x 2 3/8 in) the models with		
models		enclosure.		
Mounting methods for the cont	rol device:	To be fitted on a DIN rail, in a control panel.		
Degree of protection provided	by the covering:	:		
IP00 the open frame models		IP40 the front	of the models with enclosure.	
Connection method:				
screw terminal blocks for w	ires up to 1.5	removable screw terminal blocks for wires up		
mm ² and 2.5 mm ² the open fr	ame models	to 1.5 mm ² and 2.5 mm ² the models with		
		enclosure		
removable clamp terminal bloc	cks for wires up	Pico-Blade connector		
to 1.5 mm ² the plus controller	S			
Micro-USB connector		RJ45 F telephone connector.		
Maximum permitted length for	connection cabl	es:		
Power supply: 10 m (32.8 ft)		Analogue inputs: 10 m (32.8 ft)		
Auxiliary power supply and 0-	5 V ratiometric	Digital inputs: 10 m (32.8 ft)		
transducer power supply: 10 n	n (32.8 ft)			
0-10 V analogue outputs: 10 n	n (32.8 ft)	PWM analogue outputs: 1 m (3.28 ft)		
Digital outputs: 100 m (328 ft))	INTRABUS port: 10 m (32.8 ft)		
Unipolar or bipolar stepper ele	ctronic expansio	n valves driver: 3 m (9.84 ft)		
RS-485 MODBUS port: 1,000 r	n (3,280 ft)	USB port: 1 m (3.28 ft).		
CAN port:	1,000 m (3,28)	0 ft), baud rate:	20,000 baud	
	500 m (1,640 ft), baud rate: 50,000 baud		0,000 baud	
	250 m (820 ft), baud rate: 125,000 baud			
	50 m (164 ft), baud rate: 500,000 baud.		000 baud.	
Operating temperature:		From -10 to 55 °C (from 14 to 131 °F).		
Storage temperature:		From -20 to 70 °C (from -4 to 158 °F).		
Operating humidity:		Relative humidity without condensate from 5		
		to 95%.		
Pollution status of the control of	device:	2.		
Compliance:				
RoHS 2011/65/EC	WEEE 2012/19	/EU	REACH (EC) Regulation no. 1907/2006	
EMC 2014/30/EU		LVD 2014/35/UE.		
·				

		KIO .	KII KIZ	KIS KI4	
Power supply:			115 230 V	AC (+10% -15%), 50/60 Hz	
			(±3 Hz), max. 16 VA, 20 VA in the plus con-		
			trollers, 27 V/	A in the U-EEV and B-EEV con-	
Farthing metho	ods for the conti	ol device:	None.		
	withstand volta		2.5 KV.		
Over-voltage c			II.		
Software class	and structure:		A.		
Clock:			With secondar	y lithium battery.	
Clock drift:				at 25°C (77 °F).	
Clock battery a power supply:	autonomy in th	e absence of a	> 6 months at	t 25 °C (77 °F).	
Clock battery c	harning time:		24h (the hat	tery is charged by the power	
Clock Bucce, y c	gg cc.		supply of the		
Analogue input	s:			C or Pt 1000 probes, 8 in the	
			I	rs and in the U-EEV and B-EEV	
			I	an be configured also for dry	
			contact digital input) 5 for PTC, NTC or Pt 1000 probes, 0-5 V, 0-		
			I	A or 4-20 mA transducers, 8 in	
			I	rollers and in the U-EEV and B-	
			I	rs (can be configured also for	
270			dry contact di		
PTC probes:	Sensor type: Measurement	fiold:	KTY 81-121 (990 Ω @ 25 °C, 77 °F) from -50 to 150 °C (from -58 to 302 °F)		
	Resolution:	neid.	0.1 °C (1 °F).	30 °C (110111 -36 to 302 °F)	
NTC probes:	Sensor type:		i e	@ 25 °C, 77 °F)	
·	Measurement	field:	from -50 to 120 °C (from -58 to 248 °F)		
	Resolution:		0.1 °C (1 °F).		
Pt 1000	Sensor type:		1 KΩ @ 0 °C, 32 °F		
probes:	Measurement	field:	from -100 to 400 °C (from -148 to 752 °F)		
0-5 V trans-	Resolution:		1 °C (1 °F). ≥ 10 KΩ		
ducers:	Input resistance: Resolution:		0.01 V.		
0-10 V trans-	Input resistance	ce:	≥ 10 KΩ		
ducers:	Resolution:		0.01 V.		
0/4-20 mA	Input resistand	ce:	≤ 200 Ω		
transducers:	Resolution:	_	0.01 mA.		
	emote user inte	rfaces:	13 VDC, +20 % -10%, 150 mA max.		
Power supply t	ransuucers.		13 VDC, +20 % -10%, 100 mA max. (+40 mA max. in the plus controllers, 60 mA		
			I	and B-EEV controllers).	
Power supply 0	-5 V ratiometric	transducers:	5 VDC, ±15 9	%, 20 mA max. (+40 mA max.	
			in the plus cor		
Digital inputs:			<u> </u>	and for pulse trains up to 2 KHz	
Dry contact:		Contact type:	2 high voltage	3.3 VDC, 1 mA	
Dry contact.		Power supply:		3.5 VDC, 1 IIIA	
High voltage co	ontac:	Power supply:		115 230 VAC.	
		pansion valves	according to t	the model, 2 (12 VDC, 260 mA	
driver:			max. winding)		
	r electronic ex	pansion valves	1	the model, 2 (12 VDC, 200 mA	
driver: Analogue outpu	ıts:		max. winding). 4 for 0-10 V or PWM signal, 8 in the plus con-		
a.ogue outpt			trollers		
0-10 V sig- Minimum applicable imped-		1 ΚΩ			
nal:	ance:				
	Resolution:		0.01 V.		
PWM signal:	Power supply:		0 10 VDC, 10 mA max. 10 Hz 2 KHz		
	Prequency: Duty:		0 100%.		
Resolution:			1% up to 500 Hz, 5% up to 2 KHz.		
Digital outputs			1	electro-mechanical relay, 2 A	
			res. @ 250 VA	C, 6 in the plus controllers	
			1	electro-mechanical relay, 3 \mbox{A}	
			res. @ 250 VA		
			I	electro-mechanical relay, 3 A	
			res. @ 250 VAC, 2 in the plus controllers 2 with SPST electro-mechanical relay, 5 A		
			res. @ 250 VAC, only available in the U-EEV		
			and B-EEV controllers		
			I 1 with SPST	electro-mechanical relay, 8 A	

Example of electrical connection for U-EEV controllers.



The device guarantees:

- reinforced insulation between SELV circuits and relay outputs
- reinforced insulation between "groups" of relay outputs
- basic insulation between relay outputs belonging to the same group $% \left(1\right) =\left(1\right) \left(1\right)$
- reinforced insulation between live parts and SELV circuits
- reinforced insulation between "group 1" of relay outputs (K1... K3) and high voltage digital inputs (DIHV1 and DIHV2)

- basic insulation between live parts of opposite polarity (line-neutral).		
Type 1 or Type 2 Actions:	Type 1.	
Additional features of Type 1 or Type 2 ac-	C.	
tions:		
Communications ports:		
1 TTL MODBUS port	1 INTRABUS port (RS-485 MODBUS mas-	
	ter/slave by connecting the serial interface	
	EVIF22ISX)	
1 RS-485 MODBUS slave port	1 RS-485 port (MODBUS master/slave, BAC-	
	net MS/TP)	
1 CAN port	1 USB port	
Ethernet port (MODBUS TCP, WebServer, BACnet IP).		

200 MHz. RAM: 512 kB. Program memory: 2 MB. External FLASH: 32 MB. Memory for Web Server: 8 MB. Datalog memory:

1 with SPST electro-mechanical relay, 8 A

The device must be disposed of according to local regulations governing the collection of electrical and electronic waste.

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