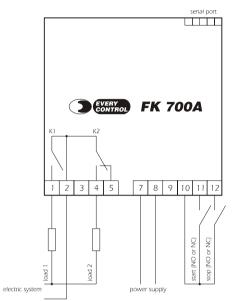
and screw brackets (on the right-hand side, by request); if you are using screw brack-

ets, you have to moderate the clamping torque, in order not to damage the box and

screw brackets

1.2 Electrical connection



2 OPERATION

2.1 Preliminary information

A full count consists of four phases:

- delay action 1
- action 1 (the load 1 will be ON)
- delay action 2

• action 2 (the load 2 will be ON and the buzzer will utter the

sound you have set with the parameter t3).

As soon as one phase will end, the instrument will automatically move to the following one.

2.2 How to start the count

If you have to start the count:

(3) start press

(3) if the parameter t4 has value 0000, you could activate the input for remote start

as well; if the parameter t4 has value 0002, you will have to activate this input.

2.3 How to suspend/resume the count

If you have to suspend/resume the count:

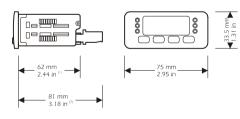
press start (4)



1 PREPARATIONS

1.1 How to install the instrument

Panel mounting, panel cut out 71 x 29 mm (2.79 x 1.14 in), with click brackets (they are supplied by the builder) or screw brackets (by request).

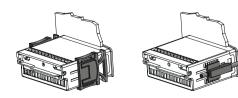


(1) maximum depth with screw terminal blocks

1/2 Sheet

800

maximum depth with extractable terminal blocks. (Z)





| (4) | if the parameter | r t8 has value | 0000, th | e function | will not I | be available; if the |
|-----|------------------|----------------|----------|------------|------------|----------------------|
|-----|------------------|----------------|----------|------------|------------|----------------------|

parameter t8 has value 0002, you will have to deactivate the input for remote

start.

2.4 How to stop the count

If you have to stop the count:

press (stop)

(5) if the parameter t5 has value 0000, you could activate the input for remote stop

as well; if the parameter t5 has value 0002, you will have to activate this input.

(5)

3 COUNT PHASES

| 3.1 | How to | set the | count | phases | lenath |
|-----|--------|---------|-------|--------|--------|
| | | | | | |

Every phase is associated with a label:

| action 1 | label E [] n 1 ⁽⁶⁾ |
|------------------------------------|--------------------------------------|
| delay action 2 | label P A U S (7) |
| action 2 | label E 🖸 n Z 🕫 |

delay action 1

If you have to modify the length of one of the phases:

press and release set

for selecting the label: the most significant part of **5.1 Signals**

the display will flash $^{(10)}$.

during the modification of

the most significant part,

If you have to modify the value of the most significant part of the

display:

```
    press (start) Or (stop)
```

If you have to modify the value of the least significant part of the

display: • press

set

then ... within 2 s

within 2 s

press
 (start) Or (stop)

If you have to quit the procedure:

• press set

(6) you can set the length of action 1 with the parameter tOn1 as well; the times base depends on the parameter t10

(7) you can set the length of delay action 2 with the parameter t20 as well; the times base depends on the parameter t0

(B) you can set the length of action 2 with the parameter t24 as well; the times base

depends on the parameter t23

(9) you can set the length of delay action 1 with the parameter t11 as well; the times

base depends on the parameter t0

(10) the labels the instrument has to show depend on the parameter t35.

| 4 | CONFIGURATION PARAM | METERS |
|---------|--|---------------------------------------|
| 4.1 | How to set the configur | ation parameters |
| lf you | have to gain access the proce | edure: |
| pres | ss (start)and(stop) | for 4 s |
| | | will show 占 🛛 |
| lf you | have to select a parameter: | |
| pres | S (start) Or (stop) | |
| lf you | have to modify the value of the | ne parameter (11) : |
| pres | is set | |
| pres | S (start) Or (stop) | within 2 s |
| pres | S (set) | |
| lf you | have to quit the procedure: | |
| pres | start)and(stop) | for 4 s 🏹 or do not op- |
| | | erate for about 60 s. |
| (11) if | you have to modify the value of the para | meters t11, t20, t24 and tOn1 use the |
| ρ | rocedure indicated at chapter 3. | |
| 5 | SIGNALS | |

MEANING

6 ALARMS

Load 1 LED

Load 2 LED

if it is lighted, action 1 will be running

if it is lighted, action 2 will be running

LED

out 1

out 2

| 6.1 A | larms | | | |
|-----------|-------------------------|--|--|--|
| CODE | REASONS | REMEDIES | EFFECTS | |
| EP | there is the corruption | switch off the power | you can not gain ac- | |
| corrupted | of the configuration | supply of the instru- | cess the setting pro- | |
| memory | data of the memory of | ment: unless the alarm | cedures | |
| data | the instrument | disappears, you will | all outputs will be | |
| | | have to change the | forced OFF | |
| | | instrument | | |
| indica- | there has been a lack | test the instrument- | the instrument will in- | |
| tion | of power supply dur- | power supply con- | terrupt the count | |
| count | ing the count | nection (look at the | | |
| inter- | | parameter t36) | | |
| rupted | | interrupt the count | | |

| indica- | there has been a lack | • test the instrument- | the instrument will |
|---------|-----------------------|---|------------------------|
| tion | of power supply dur- | power supply con- | resume the count |
| count | ing the count | nection (look at the | since the beginning |
| inter- | | parameter t36) | of the phase during |
| rupted | | interrupt the count | which the lack of |
| | | | power supply has |
| | | | taken place or since |
| | | | the lack of power sup- |
| | | | ply has taken place |
| | | | with a maximum error |
| | | | of 60 s |

The instrument shows the indications above flashing and the buzzer utters the sound

you have set with the parameter t3.

7 TECHNICAL DATA

7.1 Technical data

Box: self-extinguishing grey.

Size: 75 x 33.5 x 81 mm (2.95 x 1.31 x 3.18 in) the model with extractable terminal blocks, 75 x 33.5 x 62 mm (2.95 x 1.31 x 2.44 in) the model with screw terminal blocks.
Installation: panel mounting, panel cut out 71 x 29 mm (2.79 x 1.14 in), with click brackets (they are supplied by the builder) or screw brackets (by request).

Frontal protection: IP 65.

Connections: extractable terminal blocks with pitch 5 mm (0.19 in) for cables up to 2.5 mm² (0.38 sq in, power supply, inputs and outputs) or screw terminal blocks with pitch 5 mm (0.19 in) for cables up to 2.5 mm² (0.38 sq in, power supply, inputs and outputs), 5 poles single line male connector with pitch 2.5 mm (0.09 in, serial port). **Ambient temperature:** from 0 to 55 °C (32 to 131 °F, 10 ... 90% of relative humidity

without condensate).

Power supply: 12 Vac/dc, 50/60 Hz, 1.5 VA (standard model) or 12-24 Vac/dc, 50/60 Hz, 1.5 VA (by request).

Alarm buzzer: included.

tors.

Digital inputs: 2 inputs: one for remote start and one for remote stop (NO or NC

contact), without voltage (they work with 5 mA).

Working range: from 1 ds to 99 h and 59 min.

Display: one red LED 4-digit display 10 mm (0.39 in) high, instrument status indica-

Outputs: 2 relays: one 10 A @ 250 Vac relay for load 1 control (NO contact) and one

8 A @ 250 Vac relay for load 2 control (change-over contact).

Serial port: TTL with EVCOBUS communication protocol.

8 CONFIGURATION PARAMETERS

| 8.1 | Confi | gurat | ion para | ameters | |
|-------|-------|-------|----------|---------|---|
| LABEL | MIN. | MAX. | U.M. | DEF. | TIMER |
| tO | 0000 | 0002 | | 0000 | times base for delay action 1 and delay action 2 (it is important if t11 and/or t20 ≠ 00:00, |
| | | | | | 0000 = seconds and tenths of second, 0001 = minutes and seconds, 0002 = hours and |
| | | | | | minutes) |
| t1 | 0000 | 0001 | | 0000 | kind of contact of the remote start input (it is important if t4 ≠ 0001; 0000 = NO, 0001 = NC |
| t2 | 0000 | 0001 | | 0000 | kind of contact of the remote stop input (it is important if t5 \neq 0001; 0000 = NO, 0001 = NC, |
| t3 | 0000 | 0002 | | 0000 | sound of the buzzer during action 2 (it set the sound of the buzzer during the alarm coun |
| | | | | | interrupted as well, it is important if t24 \neq 00:00 and/or t36 \neq 0000; |
| | | | | | 0000 = it will never be activated, 0001 = continuous sound, 0002 = intermittent beep) |
| t4 | 0000 | 0002 | | 0000 | event giving the count start (0000 = by pressing the start key or activating the remote start |
| | | | | | input, $0001 = by$ pressing the start key, $0002 = by$ activating the remote start input) |
| t5 | 0000 | 0002 | | 0000 | event giving the count stop (0000 = by pressing the stop key or activating the remote stop |
| | | | | | input, $0001 = by$ pressing the stop key, $0002 = by$ activating the remote stop input) |
| t6 | 0000 | 0001 | | 0000 | kind of count the instrument has to show (it is important if t31, t32, t33 and/or t34 \neq 0000; |
| | | | | | 0000 = count down, 0001 = count up) |
| t7 | 0000 | 0001 | | 0000 | authorization to operate cyclically (it is important if t22 = 0002; 0001 = YES, as soon as one |
| | | | | | count will end, the instrument will automatically start another one) |
| t8 | 0000 | 0002 | - | 0000 | event giving the suspension/resumption of the count (0000 = no events, 0001 = in accord- |
| | | | | | ance with t4, 0002 = by deactivating the remote start input) |
| t10 | 0000 | 0002 | | 0000 | times base for action 1 (it is important if tOn 1 \neq 00:00; 0000 = seconds and tenths of second, |
| | | | | | 0001 = minutes and seconds, 0002 = hours and minutes) |
| t11 | 00:00 | (12) | (12) | 00:00 | delay action 1 length |
| t12 | 0000 | 0001 | | 0000 | load 1 operation (0000 = it will be ON during action 1 and OFF otherwise, 0001 = it will be |
| | | | | | OFF during action 1 and ON otherwise) |
| t20 | 00:00 | (12) | (12) | 00:00 | delay action 2 length |
| t21 | 0000 | 0001 | - | 0000 | load 2 operation (0000 = it will be ON during action 2 and OFF otherwise, 0001 = it will be |
| | | | | | OFF during action 2 and ON otherwise) |
| t22 | 0000 | 0002 | - | 0000 | event ending action 2 (0000 = in accordance with t5, 0001 = in accordance with t4 or t5, |
| | | | | | 0002 = in accordance with t5 or as soon as action 2 length will be passed) |
| t23 | 0000 | 0002 | - | 0000 | times base for action 2 (it is important if $t24 \neq 00:00$; $0000 =$ seconds and tenths of second, |
| | | | | | 0001 = minutes and seconds, 0002 = hours and minutes) |
| t24 | 00:00 | (13) | (13) | 00:00 | action 2 length |
| t25 | 0000 | 0002 | - | 0000 | connection between loads (0000 = no connections, 0001 = the load 2 will work in accord- |
| | | | | | ance with load 1, 0002 = the load 1 will work in accordance with load 2) (14) |
| t31 | 0000 | 0001 | — | 0000 | count showing during delay action 1 (it is important if t11 \neq 00:00; 0001 = YES) |
| t32 | 0000 | 0001 | - | 0001 | count showing during action 1 (it is important if tOn1 \neq 00:00; 0001 = YES) |
| t33 | 0000 | 0001 | _ | 0000 | count showing during delay action 2 (it is important if $t20 \neq 00:00$; $0001 = YES$) |

| t34 | 0000 | 0001 | 0000 | count showing during action 2 (it is important if t24 \neq 00:00; 0001 = YES) |
|-----|------|------|----------|---|
| t35 | 0000 | 0006 | 0002 | labels the instrument has to show during the procedure indicated at chapter 3 |
| | | | | (0000 = no labels, 0001 = tOn1, 0002 = tOn1 and tOn2, 0003 = tOn1, PAUS and tOn2, |
| | | | | 0004 = tOn1 and tPrE, $0005 = tOn1$, tOn2 and tPrE, $0006 = tOn1$, PAUS, tOn2 and tPrE) ^[15] |
| t36 | 0000 | 0003 | 0000 | operation after a lack of power supply during the count (0000 = the instrument will interrupt |
| | | | | the count, 0001 = the instrument will interrupt the count, the indication will flash and the |
| | | | | buzzer will utters the sound you have set with the parameter t3, 0002 = the instrument will |
| | | | | resume the count since the beginning of the phase during which the lack of power supply |
| | | | | has taken place, the indication will flash and the buzzer will utters the sound you have set |
| | | | | with the parameter t3, 0003 = it is important if t0, t10 and/or t23 \neq 0000, the instrument will |
| | | | | resume the count since the lack of power supply has taken place with a maximum error of |
| | | | | 60 s, the indication will flash and the buzzer will utters the sound you have set with the |
| | | | | parameter t3) |

| LABEL | MIN. | MAX. | U.M. | DEF. | serial network (evcobus) |
|-------|------|------|------|------|--|
| L1 | 1 | 15 | | 1 | instrument address |
| L2 | 0 | 7 | | 0 | instrument group |
| L4 | 0 | 3 | | 1 | baud rate (0 = 1,200 baud, 1 = 2,400 baud, 2 = 4,800 baud, 3 = 9,600 baud) |

| LABEL | MIN. | MAX. | U.M. | DEF. | ACTION 1 LENGTH |
|-------|-------|------|------|-------|-----------------|
| tOn1 | 00:00 | (16) | (16) | 00:00 | action 1 length |

(12) the unit of measure depends on the parameter t0: if the parameter t0 has value 0000, the maximum value of the parameter will be 99 s and 90 ds; if the parameter t0 has value 0001, the maximum value of the parameter will be 99 h and 59 s; if the parameter t0 has value 0002, the maximum value of the parameter will be 99 h and 59 min

- (13) the unit of measure depends on the parameter t23: if the parameter t23 has value 0000, the maximum value of the parameter will be 99 s and 90 ds; if the parameter t23 has value 0001, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter will be 99 hin and 59 s; if the parameter t23 has value 0002, the maximum value of the parameter t24 has value 0002.
- (14) except what you have set with the parameters t12 and t21

t

- (15) if the parameter has value 0000, the value you can set by using the procedure indicated at chapter 3 is action 1 length
- (16) the unit of measure depends on the parameter t10: if the parameter t10 has value 0000, the maximum value of the parameter will be 99 s and 90 ds; if the parameter t10 has value 0001, the maximum value of the parameter will be 99 min and 59 s; if the parameter t10 has value 0002, the maximum value of the parameter will be 99 h and 59 min.